Probabilistic forecasting of solar radiation

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7 September 2017



Acknowledgements

Funding:



Collaborators:

- Professor John Boland (UniSA)
- Associate Professor Yulia Gel (University of Texas)

Motivation

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- A probabilistic forecast:
 - provides information about all expected outcomes
 - allows one to both assess a wide range of uncertainties and facilitate decision making.

Overview

Our approach to developing a probabilistic forecast:

- $1. \ \ \text{develop a point forecast}$
- 2. develop a probabilistic forecast (prediction intervals).

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Today we will look at:

- 1. p1i1 methods
- 2. p2i2 methods
- 3. results and performance
- 4. synthetic sequences of solar radiation.

Data

Locations and Köppen-Geige climate classification system:

- Adelaide: Mediterranean
- Darwin: tropical
- Mildura: semi-arid.

Each data set consists of 10 years of hourly global horizontal irradiation (GHI) values (8 years in-sample, 2 years out-of-sample).

The hourly global horizontal irradiation (GHI) I_t for Mildura is given as

1

$$I_t = F_t + A_t + Z_t,$$

where F_t is a seasonal component, A_t is an autoregressive component (a linear combination of previous time steps), and Z_t is a noise such that $EZ_t = 0$, $EZ_tZ_l = 0$ if $t \neq l$ and $EZ_t^2 = \sigma_t^2$. That is, Z_t may be heteroscedastic.



Figure 1: Power spectrum of hourly global horizontal irradiation (GHI) for Mildura. The last three significant frequencies are not shown.

The Fourier component F_t of I_t is given as

$$F_t = \alpha_0 + \alpha_1 \times \cos \frac{2\pi t}{8760} + \beta_1 \times \sin \frac{2\pi t}{8760} + \alpha_2 \times \cos \frac{4\pi t}{8760} + \beta_2 \times \sin \frac{4\pi t}{8760} + \sum_{i=3}^{11} \sum_{n=1}^{3} \sum_{m=-1}^{1} [\alpha_i \times \cos \frac{2\pi (365n+m)t}{8760} + \beta_i \times \sin \frac{2\pi (365n+m)t}{8760}]$$

Note that in examples we have tested, the amount of the variance explained by the Fourier Series is approximately 80-85%.



Figure 2: Mildura: observed vs. Fourier global horizontal irradiation (GHI) for a clear sky day on January 2, 2003 (left panel) and a cloudy day on January 1, 2003 (right panel).



Figure 3: Plotted autocorrelation function (ACF) of the global horizontal irradiation (GHI) deseasoned residuals of Mildura, with 5% significance limits shown in red.



Figure 4: Plotted partial autocorrelation function (PACF) of the global horizontal irradiation (GHI) deseasoned residuals of Mildura, with 5% significance limits shown in red.

The ACF decaying slowly, while the PACF has significant spikes at lags one and two indicating an autoregressive model of order 2, AR(2).

However, after trying to overfit the model with an AR(3) process, it is found that the AR(3) process showed slightly better performance and the p-values for all three coefficients are significant at the 5% level.



Figure 5: Observed vs. forecast global horizontal irradiation (GHI) for a clear sky day on January 2, 2003 (left panel) and a cloudy day on January 1, 2003 (right panel).

We assume the hourly errors are heteroscedastic and that this is driven by a specific sun position.

So we place the hourly daytime errors into a 2-dimensional matrix according to sun elevation and sun hour angle.

We do this to take care of the systematic variation in variance in the GHI time series.



Figure 6: Sun map: Z_t binning matrix



Figure 7: Histograms of errors in each bin of the two-dimensional array, in respect to sun position (as described above), for Mildura.

Algorithm 1: Algorithm for generating (100- α) prediction intervals using the simplified method.

- **Data:** Out-of-sample hourly daytime forecasting model I_t with length N, and the two-dimensional array of errors binned according to sun position $B_{i,j}$.
- 1 for $t = 1, \ldots, N$ do
- 2 calculate sun elevation index *i* according to sun elevation for I_t ;
- 3 calculate sun hour angle index j according to sun hour angle for I_t ;
- 4 calculate the lower $\alpha/2$ percentile $B_{i,j}^{\alpha/2}$ from bin $B_{i,j}$;
- 5 calculate the upper $100 \alpha/2$ percentile $B_{i,j}^{100-\alpha/2}$ from bin $B_{i,j}$;
- 8 end
 - **Result:** Out-of-sample hourly daytime (100- α) upper and lower prediction interval, $L_t^{100-\alpha}$ and $U_t^{100-\alpha}$ respectively .

p1i1

A. Grantham, Y. R. Gel, and J. Boland, "Nonparametric short-term probabilistic forecasting for solar radiation," Sol. Energy, vol. 133, pp. 465–475, 2016.

New work: p2i2

We make improvements to the:

- point forecast \rightarrow i2
- probabilistic forecast \rightarrow p2



The new point forecasting method combines perfect knowledge of the day-ahead daily solar radiation with our previous point forecasting method. Obviously perfect knowledge of the day-ahead daily solar radiation is not feasible.

Ideally we would prefer to use a day-ahead daily forecast from a numerical weather prediction (NWP) model because a daily NWP forecast is known to be very accurate. However, a NWP is unavailable at this time. Instead we use perfect knowledge of the day-ahead daily value as a proxy.

The idea here is to demonstrate the potential performance improvements of combining a daily NWP with an hourly solar radiation forecast, generated from our statistical model. Statistical methods perform better at hourly time scales and NWP methods perform better at daily time scales.

In order to combine the hourly point forecasting with the known day-ahead (or a NWP day-ahead), we take the hourly Fourier F_t component for the day-ahead and scale it so that the daily sum of the scaled F_t matches the known day-ahead forecast.

i1: global systematic variation in variance of solar radiation.

- i1: global systematic variation in variance of solar radiation.
- i2: we look at conditional heteroscedasticity (change in variance).

The final errors are uncorrelated but dependent - the squared error terms, a proxy for variance, are correlated. This is the so-called ARCH effect- autoregressive conditional heteroscedastic. Usually when this happens one uses an ARCH or GARCH model for forecasting the variance.

However we found that instead an exponential smoothing form was more useful.

$$S_{t+1} = \alpha Z_t^2 + (1 - \alpha)S_t, \quad 0 < \alpha < 1, t \ge 2.$$

with $S_2 = Z_1^2$.

Since we are forecasting the variance, and then constructing a prediction interval using this, we have to perform this assuming the noise is normally distributed, which is not true.

So, we first had to use a normalising transformation, then forecast the variance, construct the PIs, and then transform back.

Conditional heteroscedastic probabilistic forecast method:

- 1. Find $F(Z_t, i, j)$, the cumulative probability of Z_t for bin i, j.
- 2. Transform Z_t according to $\gamma_t = F^{-1}(Z_t, i, j)$, with $\gamma_t \sim N(0, 1)$. Note that this is done each time according to the bin currently referenced.
- 3. Find the Exponential Smoothing forecast model $\psi_t^2 = \alpha \gamma_t^2 + (1 \alpha) \psi_t^2$, with $0 < \alpha < 1$.
- 4. Apply the forecast model to get prediction intervals for σ_t . For instance, for a 95% PI, use $\hat{\sigma}_t \pm 1.96\psi_t$
- 5. Apply the inverse transform to take these limits of the prediction intervals back to the equivalent values for \hat{R}_t . Note once again that one has to do this with reference to the particular bins according to time of day and solar elevation.
- 6. Add the Fourier Series Representation to all to get forecast plus bounds for the original data.

Preformance metrics: point forecast

Table 1: Point forecast: normalised root mean square error (NRMSE) (%)

Point forecast	Original (p1)	Known day ahead (p2)
Adelaide	19.14	15.56
Darwin	22.75	19.16
Mildura	15.29	12.34

Preformance metrics: point forecast

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Point forecast	Original (p1)	Known day ahead (p2)
Adelaide	0.72	0.39
Darwin	0.85	0.52
Mildura	1.32	0.57

Table 2: Point forecast: mean bias error (MBE) (%)

Preformance metrics: point forecast

Table 3: Point forecast: mean absolute error (MAE) (%)				
Point forecast	Original (p1)	Known day ahead (p2)		
Adelaide	13.25	10.57		
Darwin	15.86	13.22		
Mildura	10.83	8.43		

Prediction interval coverage probability (PICP) for a given confidence level α :

$$PICP = \frac{1}{L} \sum_{t=1}^{L} C_t,$$

where L is the total number of forecasts and

$$\mathcal{C}_t = egin{cases} 1, & L_t^{100-lpha} \leq I_{t+1} \leq U_t^{100-lpha}, \ 0, & ext{otherwise}. \end{cases}$$

Because coverage is easily obtained by having wider PI widths, we use the normalised averaged width (PINAW):

$$PINAW = rac{1}{LI_{max}} \sum_{t=1}^{L} (U_t^{100-\alpha} - L_t^{100-\alpha}),$$

where $I_{max} = 1000 W m^{-2}$.

The *coverage width-based criterion* (CWC) metric quantifies the trade-off between coverage and prediction interval width

$$CWC = PINAW(1 + \gamma(PICP)e^{-\mu((PICP) - \alpha)}),$$

where $\mu=10~{\rm and}$

$$\gamma = egin{cases} 0, & \textit{PICP} \geq /\textit{alpha}, \ 1, & \textit{PICP} < \textit{alpha}. \end{cases}$$

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BUT this doesn't penalise over-coverage the same as under-coverage. So we use

$$\mathcal{CWC} = \mathcal{PINAW}(1 + (\mathcal{PICP})e^{-\mu|(\mathcal{PICP})-lpha|}),$$

and treat over-coverage and under-coverage equally.



Figure 8: Adelaide: coverage width-based criterion (CWC)



Figure 9: Darwin: coverage width-based criterion (CWC)



Figure 10: Adelaide: 95% probabilistic forecast for a clear sky



Figure 11: Adelaide: 95% probabilistic forecast for a cloudy sky



Figure 12: Darwin: 95% probabilistic forecast for a clear sky



Figure 13: Darwin: 95% probabilistic forecast for a cloudy sky

Probabilistic forecasting conclusions

Results are mixed:

- Adelaide and Mildura: i2 is better than i1
- Darwin: i1 is better than i2

These results suggest that the ideal probabilistic forecasting method might be climate specific.

Coming soon: incorporate a *n*-step ahead hourly numerical weather prediction (NWP) forecast into our one-step-ahead hourly point forecast.

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The procedure for generating synthetic hourly GHI is

$$\widetilde{I}_{t} = F_{t} + \phi_{1}(F_{t-1} - \widetilde{I}_{t-1}) + \phi_{2}(F_{t-2} - \widetilde{I}_{t-2}) + \phi_{3}(F_{t-3} - \widetilde{I}_{t-3}) + Z_{t},$$

where \tilde{I}_t is the synthetic hourly GHI for time point t (in hours), F_t is the Fourier component and ϕ_1 , ϕ_2 and ϕ_3 are the coefficients for the autoregressive order three (AR(3)) component. The procedure follows the hourly model but includes a bootstrapped white noise term Z_t . The white noise term Z_t is bootstrapped (sampled with replacement) from $B_{i,j}$ (two-dimensional matrix of errors), according to the corresponding sun elevation and hour angle.

The synthetic hourly GHI will include patterns of GHI that have not occurred in the recorded data but are nonetheless equally as likely to occur. That is, the synthetic sequences have the same statistical properties as the observed:

- the same underlying hourly distributions
- the same serial hourly correlation structure
- the same underlying daily sum distribution
- the same daily serial correlation structure.



Figure 14: Example of five synthetic daily global horizontal irradiation (GHI) estimates for the month of January.



Figure 15: Example of five synthetic hourly global horizontal irradiation (GHI) estimates for January 1.

Table 4: Frequency distribution of consecutive days in 100 years with daily global horizontal irradiation (GHI) below 2,000 Wh m⁻² using the eight years of observed daily GHI, 1995–2002, and the 1,000 synthetic daily GHI \hat{I}_t^* years (instances), for Mildura.

Consecutive days	Observed	Synthetic
1	1512.5	1596.5
2	362.5	367.0
3	112.5	105.4
4	50.0	32.7
5	12.5	10.5
6	0.0	3.6
7	0.0	1.1
8	0.0	1.0
9	0.0	0.1

Synthetic sequences of GHI conclusions

The synthetic data can be used, for example, as input for testing the performance and operation of a solar energy system for all supply scenarios resulting in the design of a more reliable system.

This work is part of a bigger endeavour, where we start with synthetic yearly, then synthetic seasons from that and then daily, then hourly and then 5 minute or minute, all in a chain.